

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	2	"20070112466".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/05 19:20
S2	20	("4615515" "6886061" "4235218" "4262454" "4235218" "4262454" "5897114" "5927936" "5836577" "5813825" "5996993" "6161995"). pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:18
S3	1640	keio.as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:20
S4	411	700/3.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:21
S5	1	(kouhei with ohnishi).as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:22
S6	1	(masaki with kitajima). as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:22
S7	7	(kouhei with ohnishi).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:22
S8	23	(masaki with kitajima). in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23

S9	8	(yasuhide with morikawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23
S10	43729	(souji ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23
S11	1	(souji with ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:23
S12	550	(toshiharu with furukawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:24
S13	295	(toshiyuki with murakami).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:25
S14	70	(kazuo with nakazawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:25
S15	110	(wataru with iida).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:25
S16	3	(tomoko with yano).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:26
S17	2247	(position with force with driv\$4 with control).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:27
S18	55	(position with force with driv\$4 with control with acceleration).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:27

S19	58645	reaction adj force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:28
S20	199	S17 and S19	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:28
S21	412	(position with force with driv\$4 with control with signal).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:29
S22	5	S21 and master and slave	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:30
S23	8464	(700/3,260,2,19-21,28- 46,54-61,302).ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 01:43
S24	426	(inverted adj pendulum) and control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:21
S25	209	S24 and force and acceleration	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22
S26	0	S25 and (lab adj view)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22
S27	0	S24 and (lab adj view)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22
S28	116	S24 and (state with control)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:22

S29	78	S25 and S28	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:23
S30	36	S29 and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:23
S31	37	(inverted adj pendulum). TL	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:38
S32	161	(inverted adj pendulum) and ROD	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 19:52
S33	271	(inverted adj pendulum) and balanc\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:20
S34	27	(inverted adj pendulum) and balanc\$3 and (control adj theory)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:20
S35	0	gripper and (bilateral adj control) and acceleration and position and (control adj theory) and (reaction and force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:43
S36	11	gripper and (bilateral adj control) and acceleration and position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:43
S37	0	gripper and (bilateral adj control) and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:47
S38	1	gripper and (bilateral adj control) and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:47

S39	55	gripper and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:48
S40	3	gripper and acceleration and position and (reaction adj force) and gain and (natural adj frequency)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 20:48
S41	1	forceps and acceleration and position and (reaction adj force) and gain and (natural adj frequency)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:18
S42	10	forceps and acceleration and position and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:19
S43	212	forceps and acceleration and position and control and motor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:21
S44	169	forceps and acceleration and position and control and motor and force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:21
S45	134	forceps and acceleration and position and control and motor and force and frequenc\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:22
S46	38	forceps and acceleration and position and control and motor and force and frequenc\$4 and bilateral	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:22
S47	1	(reaction adj force) and observer and master and slave and acceleration and position and control and motor and force and frequenc\$4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:29

S48	2	observer and master and slave and acceleration and position and control and motor and force and frequenc\$4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:29
S49	13	observer and acceleration and position and control and motor and force and frequenc\$4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:30
S50	70	acceleration and position and control and motor and force and frequenc\$4 and bilateral and gain and command and linear and sensor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:31
S51	57	S50 not S49	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:31
S52	11	S51 and (forcep gripper)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:31
S53	2325	encoder and (host adj computer) and control and position and force and (noise error disturbance)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:38
S54	1883	S53 and (movement friction)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:39
S55	88	S54 and (observer observability) and (sens \$3 detect\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:40
S56	2	"20070112466".pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47

S57	20	("4615515" "6886061" "4235218" "4262454" "4235218" "4262454" "5897114" "5927936" "5836577" "5813825" "5996993" "6161995"). pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S58	1640	keio.as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S59	411	700/3.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S60	1	(kouhei with ohnishi).as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S61	1	(masaki with kitajima). as.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S62	7	(kouhei with ohnishi).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S63	23	(masaki with kitajima). in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S64	8	(yasuhide with morikawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S65	43729	(souji ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47

S66	1	(souji with ozawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S67	550	(toshiharu with furukawa).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S68	295	(toshiyuki with murakami).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S69	70	(kazuo with nakazawa). in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S70	110	(wataru with iida).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S71	3	(tomoko with yano).in.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S72	2247	(position with force with driv\$4 with control).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S73	55	(position with force with driv\$4 with control with acceleration).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S74	58645	reaction adj force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S75	199	S72 and S74	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47

S76	412	(position with force with driv\$4 with control with signal).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S77	5	S76 and master and slave	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S78	8464	(700/3,260,2,19-21,28-46,54-61,302).ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:47
S79	411	S59 and S78	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:51
S80	8464	S59 S78	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:51
S81	556	S80 and force and acceleration	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:51
S82	1	S49 and S80	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:52
S83	377	S81 and position and control and motor and force	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:53
S84	1	S39 and (bilateral adj control)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:53
S85	55	S39 and (reaction adj force)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 21:53

S86	9	("6860160" "7234729" "6728616" "6849807" "6705345").pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/02/21 22:56
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